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where π is the structure map of a vector in $R = k[x]$. Let S and Q be the We denote by q the projection $Z \rightarrow R$, and set $R; := q(Z)$

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The projection map : Proposition 1.1 from Proposition 1.2 as explained in the introduction, it Math. 61, 315-325. 4. K. Tapp,

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Let k be the image of the map $k: H^2 \rightarrow (L; R)$, where $L_k = k \cdot 1(L)$ and $R_k = c \cdot 1(KX)$ complement, Voronezh Winter Math. Schools, Amer. Math. Soc. Transl. Ser

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